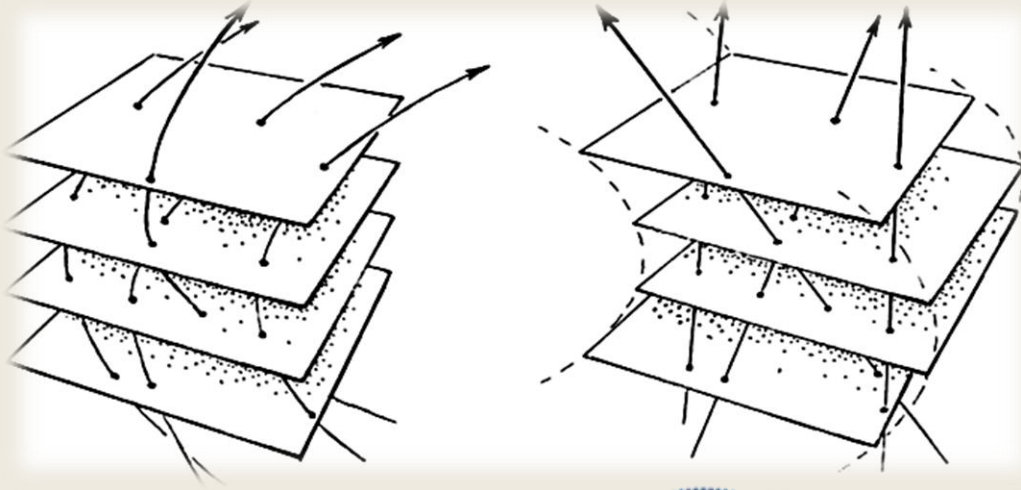
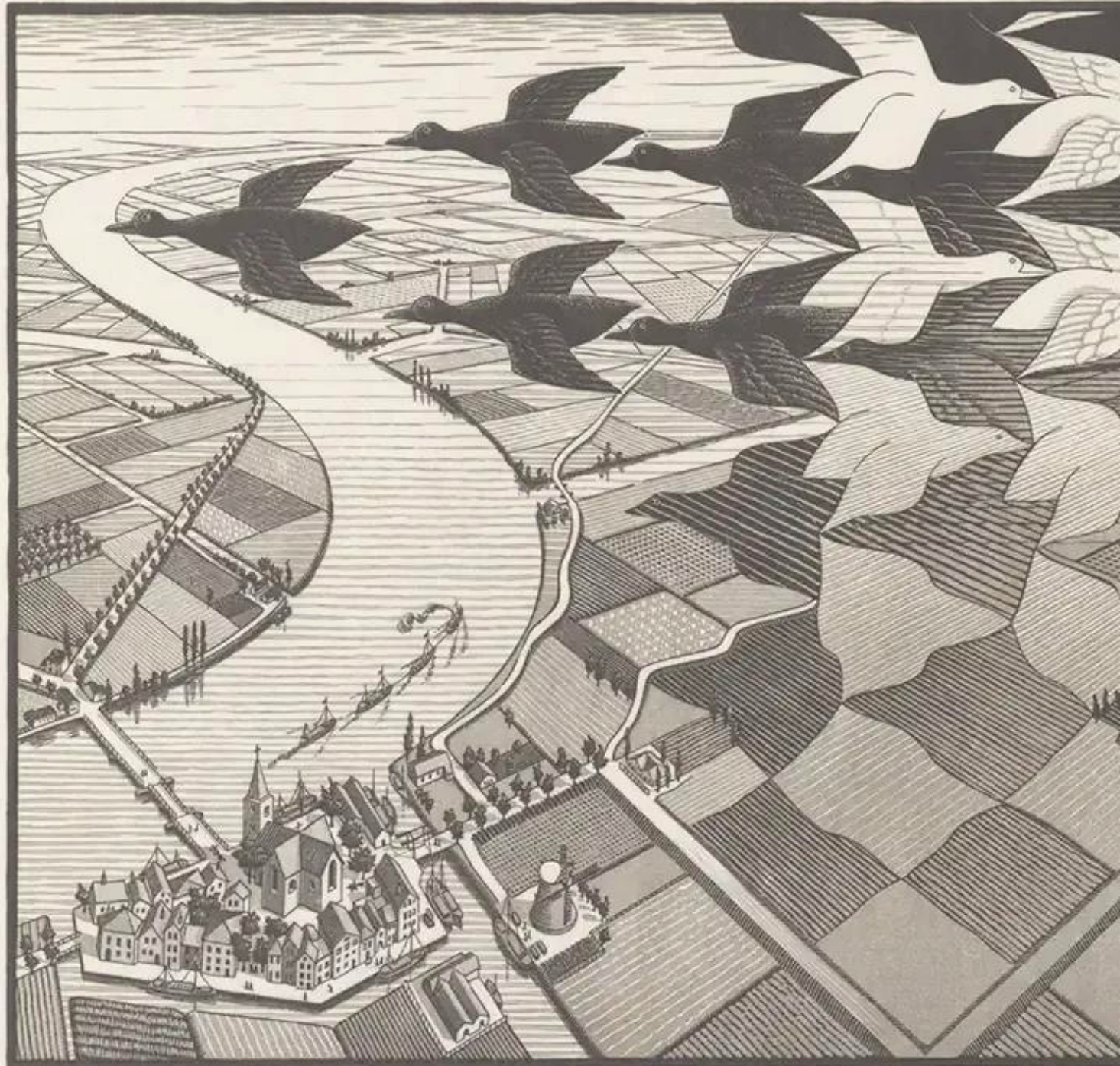


# Metric degeneracy: why relativistic gravity is less susceptible to underdetermination and separatism than Newton-Cartan theory

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BSPS, Glasgow, 16 July 2025



Supported by the American Institute of Physics



Geometric conventionalism  
through universal effects

Universal forces and (non-)  
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Metric degeneracy and  
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Unity, unitism,  
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## Synopsis


- 1) Two proofs (Weatherall & Manchak's 2014) show that:  
→ non-relativistic gravity is more susceptible than general relativity to conventionalism through “universal forces” (in some Reichenbachian sense).

But: not so obvious why this discrepancy arises.

- 2) A recently clarified metaphysical view “unitism” and its anti-thesis “separatism” (Gilmore, Costa, Calosi 2016).  
→ are space and time just different kinds of spacetime or are they separate entities?

But: not obvious what mathematical underpinnings support unitism / separatism.

**Claim:** *Metric degeneracy* is the crucial disanalogy between relativistic and non-relativistic spacetime theories that underlies underdetermination and support for separatism of Newton-Cartan theory.



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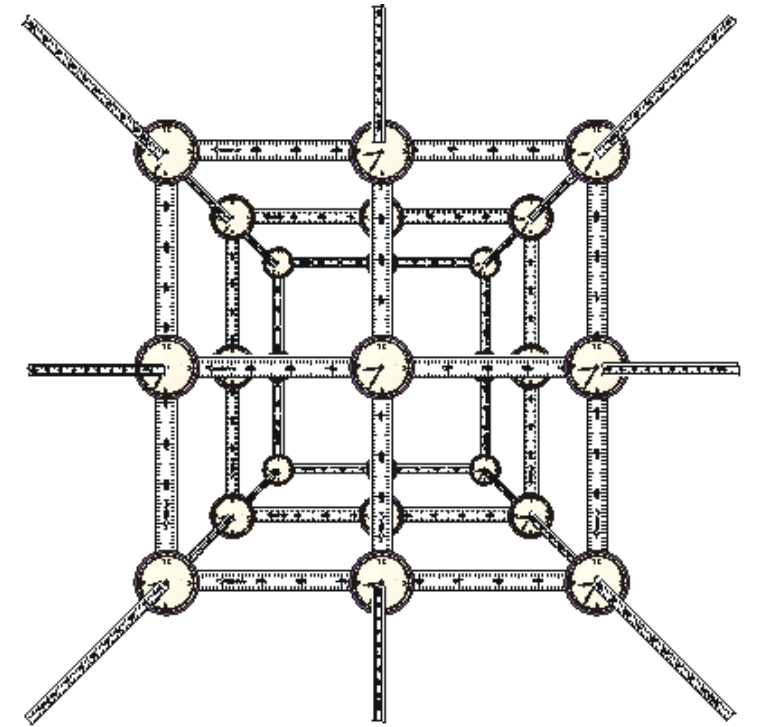
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# Universal “forces”: 100 years of trading off geometries (1/3)

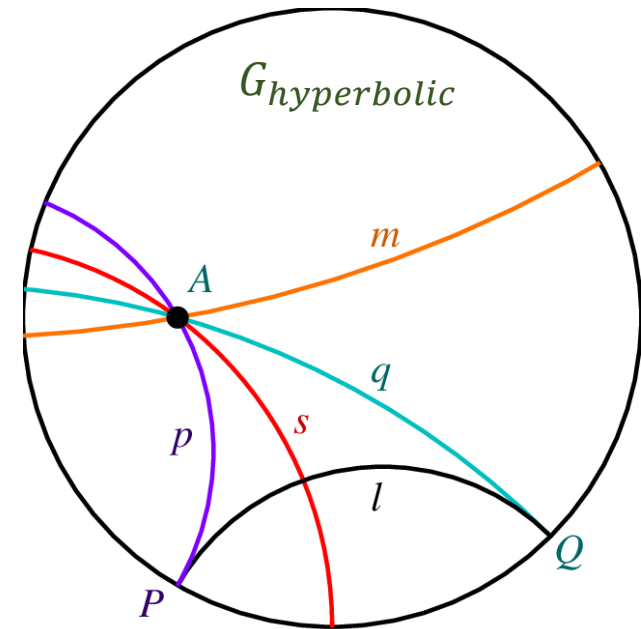
Physical geometry (Helmholtz 1866): empirical question for the *physical* geometry of the world: rods and clocks.



# Universal “forces”: 100 years of trading off geometries (2/3)

Physical geometry (Helmholtz 1866): empirical question for the *physical geometry* of the world: rods and clocks.

Geometric holism based on Poincaré’s equivalent proofs (1891): there are many empirically equivalent combinations of geometries  $[G]$  and “universal forces” (“universal effects”)  $[F]$ :  $\{G+F, G'+F', G''+F'', \dots\}$ .



# Universal “forces”: 100 years of trading off geometries (3/3)

Physical geometry (Helmholtz 1866): empirical question for the *physical geometry* of the world: rods and clocks.

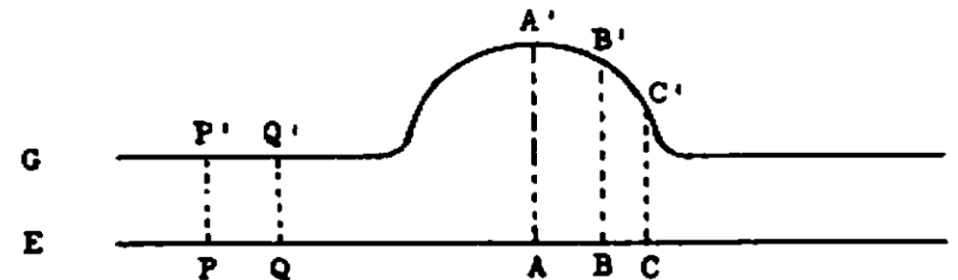
Geometric holism based on Poincaré’s equivalent proofs (1891): there are many empirically equivalent combinations of geometries  $[G]$  and “universal forces” (“universal effects”)  $[F]$ :  $\{G+F, G'+F', G''+F'', \dots\}$ .


Conventionalism about space(time): ascertaining the physical geometry requires (in some way) a conventional choice.  
→ Loosely associated with Poincaré, Duhem, Schlick, Carnap, and others, and Reichenbach (1926, Sec. 8):

**Theorem  $\theta$ :** “Given a geometry  $G'$  to which the measuring instruments conform, we can imagine a universal force  $F$  which affects the instruments in such a way that the actual geometry is an arbitrary geometry  $G$ , while the observed deviation from  $G$  is due to a universal deformation of the measuring instruments.”<sup>1</sup>

Theorem  $\theta$  shows all geometries to be equivalent; it formulates the *principle of the relativity of geometry*. It follows that it is meaningless to speak about one geometry as the *true* geometry.

An effect (force) is universal iff it  
1. cannot be screened off by insulating walls  
2. acts equally on all materials/particle species  
Otherwise it is a differential effect (or force)





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# Weatherall & Manchak (2014): “The Geometry of Conventionality”

Can these trade-offs between geometry and universal forces *always* be made given the mathematics of modern spacetime theories?

Weatherall & Manchak prove that – given a force field in the “standard sense” (i.e., acting on a test body in the geodesic equation like a rank-2 tensor):

→ **Proposition 1. (Geometrised) Newtonian gravity:** yes, this is always possible.

→ **Proposition 2. General relativity:** no, this is not always possible.

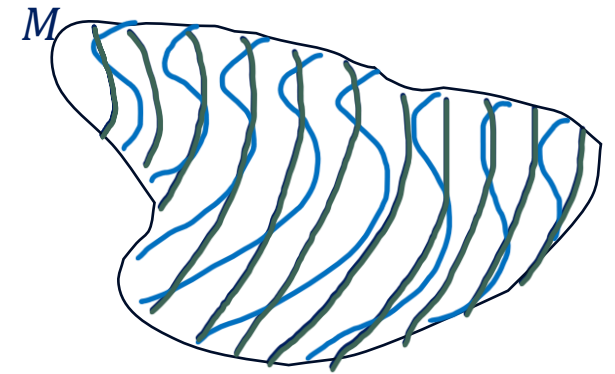
Striking:

- (i) Much-needed **rigour** to a conceptual debate;
- (ii) Explicit **theory-dependence**;

However, there is enough to clarify:

- (iii) Are the **assumptions** justified? (Dürr & Ben-Menahem 2022, Mulder 202?a)
- (iv) Little engagement with **Reichenbach’s project**;
- (v) No explanation / discussion of the **discrepancy**!

Spacetime  $(M, g, \nabla)$   
→ geodesics:  $\xi^b \nabla_b \xi^a = 0$



Spacetime  $(M, \tilde{g}, \tilde{\nabla})$   
→ geodesics:  $\tilde{\xi}^b \tilde{\nabla}_b \tilde{\xi}^a = 0$

Spacetime  $(M, \tilde{g}, \tilde{\nabla})$   
→ dynamics:  $\tilde{\xi}^b \tilde{\nabla}_b \tilde{\xi}^a + F^a_b \tilde{\xi}^b = 0$



# Proposition 1: Newtonian gravity is underdetermined

## The non-relativistic case (Prop. 1.)

*Fix a classical spacetime  $(M, t_a, h^{ab}, \nabla)$  and consider an arbitrary torsion-free derivative operator on  $M$ ,  $\tilde{\nabla}$ , which we assume to be compatible with  $t_a$  and  $h^{ab}$ . Then there exists a unique antisymmetric field  $F^{ab}$  such that given any timelike curve  $\gamma$  with unit tangent vector field  $\xi^a$ ,  $\xi^n \nabla_n \xi^a = 0$  iff  $\xi^n \tilde{\nabla}_n \xi^a = F^a_n \xi^n$ , where  $F^a_n = h^{am} F_{mn} \xi^n$ . (W&M, p. 240)*



Newton-Cartan theory has (pseudo-)metrics  $t_a$  and  $h^{ab}$ .

We look at the difference tensor  $C^a_{bc}$  defined between two connections:  $\nabla = (\tilde{\nabla}, C)$ .

(Malament 2012, Prop (4.1.3): If  $\nabla$  is compatible with both  $(\nabla_b t_a = 0 = \nabla_b h^{ab})$  then  $\tilde{\nabla}$  is compatible with  $t_a$  and  $h^{ab}$  iff  $C$  is of the form  $C^a_{bc} = 2h^{an} t_{(b} \kappa_{c)n}$ , for  $\kappa$  a smooth anti-symmetric field.

Then compute the acceleration in the new geometry (on a  $\nabla$ -geodesic of the old geometry):

$$\tilde{\alpha}^a = \xi^b \tilde{\nabla}_b \xi^a = -C^a_{nm} \xi^n \xi^m = -2h^{ar} t_{(n} \kappa_{m)r} \xi^n \xi^m = -2h^{ar} F_{mr} \xi^m,$$

for  $F_{mr} = t_{(n} \kappa_{m)r}$  making good geometric sense (e.g., acts similarly to the Faraday tensor)

# Proposition 2: GR is less susceptible to underdetermination

## The relativistic case (Prop. 2.)

*Let  $(M, g_{ab})$  be a relativistic spacetime, let  $\tilde{g}_{ab} = \Omega^2 g_{ab}$  be a metric conformally equivalent to  $g_{ab}$  and let  $\nabla$  and  $\tilde{\nabla}$  be the Levi-Civita derivative operators compatible with  $g_{ab}$  and  $\tilde{g}_{ab}$ , respectively. Suppose  $\Omega$  is nonconstant. Then there is no tensor field  $F_{ab}$  such that an arbitrary curve  $\gamma$  is a geodesic relative to  $\nabla$  if and only if its acceleration relative to  $\tilde{\nabla}$  is given by  $F^a_n \tilde{\xi}^n$ , where  $\tilde{\xi}^n$  is the tangent field to  $\gamma$  with unit length relative to  $\tilde{g}_{ab}$ . (W&M, p. 242-3)*



Compute the difference tensor  $C$  (for  $\nabla = (\tilde{\nabla}, C)$ ) for *conformally equivalent* spacetimes ( $\tilde{g}_{bc} = \Omega^2 g_{bc}$ ):

$$C^a_{bc} = \frac{1}{2} g^{an} (\nabla_n g_{bc} - \nabla_b g_{nc} - \nabla_c g_{bn}) = \frac{1}{2\Omega^2} (g_{bc} g^{an} \nabla_n \Omega^2 - \delta_c^a \nabla_b \Omega^2 - \delta_b^a \nabla_c \Omega^2).$$

With normalization  $g_{ab} \xi^a \xi^b = 1 = \tilde{g}_{ab} \tilde{\xi}^a \tilde{\xi}^b = g_{ab} \Omega^2 \tilde{\xi}^a \tilde{\xi}^b \rightarrow \tilde{\xi}^a = \Omega^{-1} \xi^a$ .


Geodesic equation  $\tilde{\xi}^b \tilde{\nabla}_b \tilde{\xi}^a = \tilde{\xi}^b \nabla_b \tilde{\xi}^a + C^a_{bc} \tilde{\xi}^a \tilde{\xi}^b = \dots = \dots = \frac{1}{\Omega^3} (\xi^b \xi^c - g^{an}) \nabla_n \Omega$ .

If  $F_{ab}$  exists, then (on a  $\nabla$ -geodesic):  $\tilde{\xi}^b \tilde{\nabla}_b \tilde{\xi}^a = F^a_m \tilde{\xi}^m = \frac{1}{\Omega} \tilde{g}^{an} F_{nm} \tilde{\xi}^m = \frac{1}{\Omega^3} (\xi^b \xi^c - g^{an}) \nabla_n \Omega$ .

→ This leads to a contradiction

→ Thus no  $F_{ab}$  exists for GR!

→ But W&M don't dwell at length on why this difference arises.



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# Metric *non*-degeneracy

A semi-Riemannian metric on manifold  $M$  is a smooth symmetric rank-2 tensor field  $g_{ab}$  that is **invertible** :

(1) There exists a tensor field  $g^{bc}$  on  $M$  such that  $g_{ab}g^{bc} = \delta_a^c$ .

If this holds then  $g_{ab}$  is called *non-degenerate*.

→ this is a **local notion**: a metric is degenerate at point  $p \in M$  if the bilinear  $g_p: T_p M \times T_p M \rightarrow \mathbb{R}$  is degenerate.

But this is **equivalent** to the statement that (see Malament 2012, p.74):

(2) For all  $p$  in  $M$ , and all vectors at  $p$ , if  $g_{ab}\xi^a = \mathbf{0}$ , then  $\xi^a = \mathbf{0}$ .

Thus, the contraction map  $g_{ab}\xi^a \mapsto \xi^a$  is **injective**: the only vector send to zero is the zero vector.

→ Every vector  $\xi^a \in T_p M$  can be uniquely associated with a covector  $\omega_a \in T_p^* M$ .

→ This is not the case in Newton-Cartan theory.

# Metric degeneracy: why there exist an $F_{ab}$ for NCT but not for GR

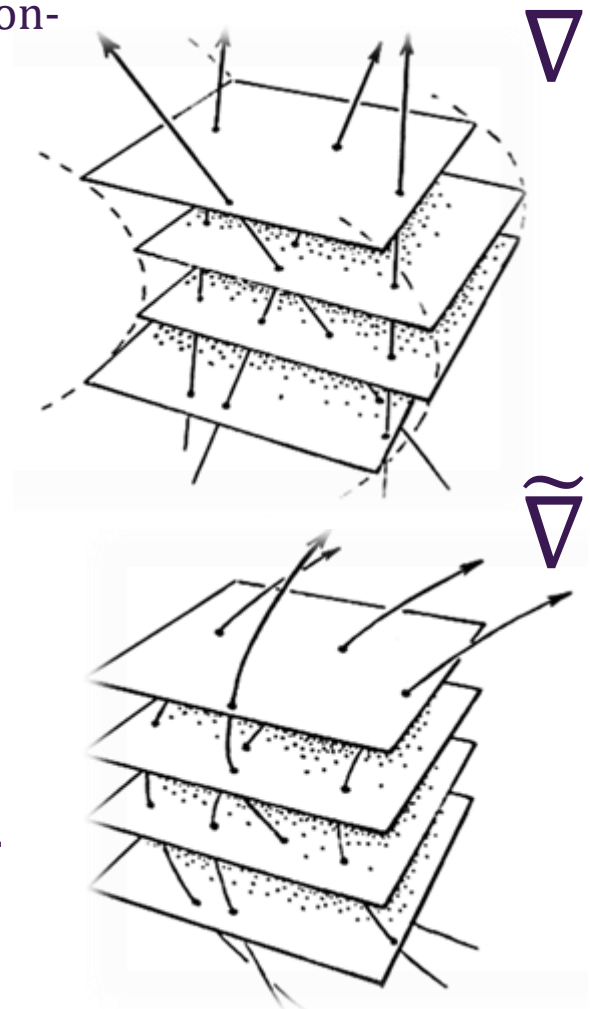
In Newton-Cartan theory the (pseudo-)metrics  $t_a, h^{ab}$  are *degenerate*: there are non-zero vectors that get assigned zero “length” in  $T_p M$ :

- $h^{ab}$  annihilates anything temporal: it can project onto space, but it cannot give inner products of arbitrary vectors.
- range of  $h^{ab}$  lies entirely in the subspace of the tangent space orthogonal to  $t_a$ . That is  $h^{ab}t_a = 0$ .
- $t_a$  defines a preferred direction in spacetime.
- Other than in GR, there is *no unique* connection compatible with  $t_a$  and  $h^{ab}$ :  
 $\nabla t = \nabla h = 0$  and  $\tilde{\nabla} t = \tilde{\nabla} h = 0$  . Yet:  $\tilde{\nabla} \neq \nabla$
- Spatial relations within each leaf are still agreed upon.

Thus, underdetermination arises as multiple correct ways to link the leafs through **motion**, namely (By Prop (1)):  $a^a = \xi^b \nabla_b \xi^a = 0$  or  $\tilde{a}^a = \xi^b \tilde{\nabla}_b \xi^a = -2h^{ar} F_{mr} \xi^m$ .

In GR, the metric uniquely determines the connection: any change in connection requires a change in the metric

→ this is why it cannot be captured by a standard force field  $F_{ab}$ .





# Conventionalism, incompleteness, and the Kaluza-Klein miracle

Roberts (202?) argues that conventionalism is a consequences of **incompleteness**.

Main example. Through the **Nash embedding theorem** one can take any manifold and represent it as a smooth surface inside a higher-dimensional flat space (isometrically).

- Intrinsic curvature is turned into extrinsic curvature via embedding functions:
- Take a GR model  $(M, g)$  and embed it isometrically into a 5D flat space  $(\mathbb{R}^5, G_{AB})$  with embedding map  $\phi: M \hookrightarrow \mathbb{R}^5$  such that  $g_{ab}(x) = \partial_a \phi^A(x) \partial_b \phi^B(x) G_{AB}$ .
- Extrinsic curvature is not uniquely fixed by the intrinsic geometry.

→ **Dimensional conventionality**: any geometry we experience could be viewed as the result of embedding into a higher-dimensional flat space!


→ **Embedding map conventionality**: Nash's theorem guarantees existence of  $\phi$ , not uniqueness: typically there are many  $\phi$ 's per  $g$ .

The “**Kaluza-Klein miracle**”: unification through compactification 5<sup>th</sup> dimension: both GR and EM emerge from a single geometric structure that is physically motivated and is such that the choice of geometry is no longer arbitrary.

Does that mean **NCT incomplete** in Roberts' sense? I think so...

→ It does not uniquely determine the affine structure: **multiple empirically indistinguishable but geometrically distinct models**, which (in Roberts' sense) leaves too much room for conventions and needs to be “completed”.





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# Unitism and Separatism

Inspired by Minkowski:

“Henceforth space by itself, and time by itself, are doomed to fade away into mere shadows, and only a kind of union of the two will preserve an independent reality”

Gilmore, Costa, Calosi (2016) observe there are **three** four-dimensionalisms:

1. B-theory (of time) as opposed to non-B-theory (like A-theory)
2. Perdurantism as opposed to Endurantism
3. Unitism as opposed to Separatism

The idea is to ask whether space and time are “unified” into spacetime or maintain “separate” metaphysical distinctness.

Are ‘points in space’ & ‘instances of time’ are just sorts of ‘spacetime events’?

How to make that more precise?



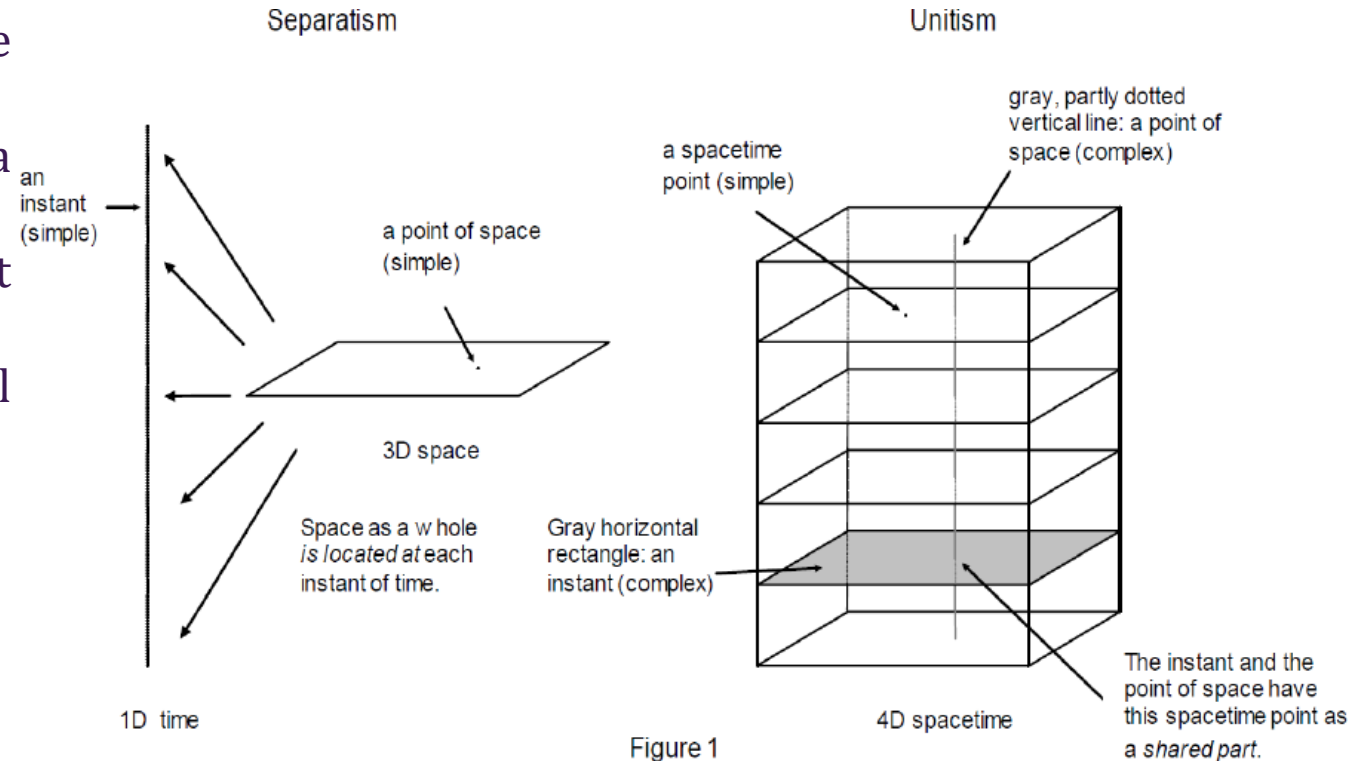
# Formulating Unitism and Separatism

## Several clarifications of unitism:

1. 'Points in space' & 'instances of time' are just sorts of 'spacetime events';
2. Spatiotemporal distances are invariant, while spatial and temporal distances are not;
3. Nothing can exist at a time while not existing at a space, or *vice versa*;
4. Space and time are unified in a 4D manifold. (not specified in what way);
5. Spacetime points are 'simples', more fundamental than complex entities space and time.

## And of separatism:

1. Space and time do not have shared parts;
2. Space *persists* through time (i.e., denial of perdurantism about space);
3. Space is entirely made of spatial points.



# Metric degeneracy of Newton-Cartan is what supports Separatism

## Metric degeneracy by itself supports Separatism:

- For NCT,  $t_a$  and  $h^{ab}$  naturally mirror a separatist ontology:
  - there is no single unified metric uniting space and time into a unique 4D geometric structure
  - space and time are primitive “simples”
  - nor are there invariant 4D intervals (like  $ds^2 = g_{\mu\nu}dx^\mu dx^\nu$ )
  - in principle, it makes semantical sense to exist in time but not in space.
  - NCT is incomplete: there are conventional choices to be made how to attach a spatial slice at each time instant.
- In general, degeneracy by itself is a sufficient condition to support Separatism:
  - If the kernel contains not just the zero vector, then some non-zero vectors that get assigned zero length.
  - Space and time cannot be attached to each other in a **unique** way!


## NCT in Separatist terms (NCT-I):

- Time evolves and space evolves through time.
- **Dynamics** describes temporal evolution of spatial configurations.

## NCT in Unitist terms? (NCT-II):

- **Demand** that the split into “space” and “time” is not absolute: all geometry is encoded in a full 4D structure.
- Requires extra conditions: a unique (global) connection  $\nabla$  determined by **mass distribution + Trautman conditions**.
- Dynamics is just geometric structure constraining worldlines.





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